

CN410 Fundamentals of Differential GNSS applications
September 22, 2009, 8:30 am-12:00 pm, CEU: 3.0
GNSS Solutions® Tutorials prior to ION GNSS 2009, September 21-22, 2009
Marriott Savannah Riverfront, Savannah, GA

Instructor: Dr. Hans-Jürgen Euler, Owner inPosition gmbh, Switzerland

Prerequisite: Knowledge of mathematics, computer science, and introduction to satellite navigation systems (e.g., CN406 Fundamentals of GNSS using GPS II) will be useful.

Intended Audience: Engineers, scientists, and managers involved with the design, development, implementation, and/or use of systems using GPS, Galileo, and/or Glonass. The course provides a solid basis in the fundamentals of differential satellite navigation and in particular details on various error mitigation techniques and method for applications of various baseline lengths and performance requirements. The course is more advanced than a simple introduction to GNSS course, but not too advanced for the beginner to GNSS.

Notes Provided: Slides presented will be professionally spiral bound, with clear plastic cover, including color to add clarity where needed.

Reference List: A reference list will be provided as part of the note package for completeness and to allow the interested attendee to obtain additional information.

Course Overview: This course emphasizes the fundamentals of differential GNSS baseline techniques with focus on DGPS and an introduction to differential GPS RTK applications. The course will explore the various error mitigation techniques and methods for improving the navigation position based on GNSS. The first section of the course builds up knowledge on DGPS with its sub-meter accuracy. The second half of the course will also target an introduction to high precision positioning. Performance aspects with respect to accuracy, integrity, continuity, and availability will be presented.

Course Content: The main topics to be covered by this course are:

- Introduction to differential GNSS techniques and different ways to implement it- (overview)
- Overview of error sources in GNSS applications
 - Satellite and receiver dependent errors
 - Atmospheric refraction
 - Antenna and multi-path errors
- Differential pseudorange-based navigation
 - Error Mitigation Techniques
- Overview of differential services available
 - Space-Based Augmentation Systems (SBAS) (e.g., WAAS, EGNOS, etc.)
 - Local Area Augmentation Systems
 - Commercial services
- Introduction to Precise Differential Techniques
- Carrier phase ambiguities
- The Mitigation of Antenna Errors

- Multi-frequency advantages
- Summary of standards for RTK applications
 - RTCM SC104 V2
 - RTCM SC104 V3

Course Outcomes: At the completion of this course, the attendee should have the ability to understand the fundamentals of differential GNSS systems in the presence of measurement errors. The DGNSS and RTK approaches based on different correction information can be differentiated. The principle concept of RTK can be rated in comparison with the lower precision DGNSS. For further error mitigation using differential GNSS techniques, CN415 Fundamentals of GNSS Baseline RTK and Network RTK applications is recommended.